

Faster Algorithms for Graph Monopolarity

G. Philip¹ and Shrinidhi T. Sridhara²

¹*Chennai Mathematical Institute, India*

²*Université de Bordeaux, France*

WG 2025



Monopolar Recognition

- **Input:** A graph $G = (V, E)$ on n vertices
 - **Question:** Is there a partition $V = C \uplus I$ such that $G[C]$ is a *cluster graph* and I is an *independent set*?
-

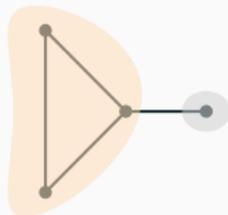
Monopolar Recognition

- **Input:** A graph $G = (V, E)$ on n vertices
 - **Question:** Is there a partition $V = C \uplus I$ such that $G[C]$ is a *cluster graph* and I is an *independent set*?
-



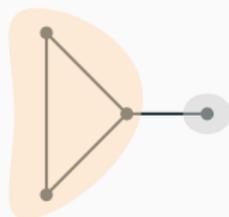
Monopolar Recognition

- **Input:** A graph $G = (V, E)$ on n vertices
 - **Question:** Is there a partition $V = C \uplus I$ such that $G[C]$ is a *cluster graph* and I is an *independent set*?
-



Monopolar Recognition

- **Input:** A graph $G = (V, E)$ on n vertices
 - **Question:** Is there a partition $V = C \uplus I$ such that $G[C]$ is a *cluster graph* and I is an *independent set*?
-

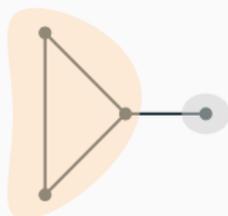


Monopolar

The Problem

Monopolar Recognition

- **Input:** A graph $G = (V, E)$ on n vertices
 - **Question:** Is there a partition $V = C \uplus I$ such that $G[C]$ is a *cluster graph* and I is an *independent set*?
-



Monopolar



Not Monopolar

Monopolarity: Some History

- Well-studied - graphclasses.org
- “Lighter version” of *polar* graphs*
 - Partitioning into a cluster graph and a *co-cluster* graph
 - Polar Recognition is **NP-complete** in very restricted classes like claw-free graphs[†]

*Tyshkevich and Chernyak, *Decomposition of graphs*, 1985

[†]Churchley and Huang, *On the polarity and monopolarity of graphs*, 2013

[‡]Farrugia, *Vertex-partitioning into fixed additive induced-hereditary properties is NP-hard*, 2004

[§]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

Monopolarity: Some History

- Well-studied - graphclasses.org
- “Lighter version” of *polar* graphs*
 - Partitioning into a cluster graph and a *co-cluster* graph
 - Polar Recognition is **NP-complete** in very restricted classes like claw-free graphs[†]
- Monopolar Recognition is **NP-complete**[‡], also in some restricted classes
 - E.g., triangle-free planar graphs[§] of maximum degree 3
- Our main result: a **fast exponential-time algorithm** for Monopolar Recognition

*Tyshkevich and Chernyak, *Decomposition of graphs*, 1985

†Churchley and Huang, *On the polarity and monopolarity of graphs*, 2013

‡Farrugia, *Vertex-partitioning into fixed additive induced-hereditary properties is NP-hard*, 2004

§Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

Some Easy Exact Algorithms for Monopolar Recognition

- The straightforward algorithm:
 - Go over all partitions of V into two parts $V = C \uplus I$
 - Takes $\mathcal{O}^*(2^n)$ time

Some Easy Exact Algorithms for Monopolar Recognition

- The straightforward algorithm:
 - Go over all partitions of V into two parts $V = C \uplus I$
 - Takes $\mathcal{O}^*(2^n)$ time

- Easy improvement to $\mathcal{O}^*(1.4423^n)$
 - **Observation:** If G has a monopolar partition, then it has one where the independent set is *inclusion-maximal*
 - Go over all *maximal* independent sets $I \subseteq V$
 - Can be done in $\mathcal{O}^*(3^{n/3}) = \mathcal{O}^*(1.4423^n)$ time^a

^aJohnson et al., *On generating all maximal independent sets*, 1988

Our Results

- We solve Monopolar Recognition in $\mathcal{O}^*(1.3734^n)$ time
 - Improves on the $\mathcal{O}^*(1.4423^n)$
 - Also finds a monopolar partition, if the graph is monopolar

*Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Our Results

- We solve Monopolar Recognition in $\mathcal{O}^*(1.3734^n)$ time
 - Improves on the $\mathcal{O}^*(1.4423^n)$
 - Also finds a monopolar partition, if the graph is monopolar
- This talk: a **simpler version** that solves Monopolar Recognition in $\mathcal{O}^*(2^{n/2}) = \mathcal{O}^*(1.4142^n)$ time

*Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Our Results

- We solve Monopolar Recognition in $\mathcal{O}^*(1.3734^n)$ time
 - Improves on the $\mathcal{O}^*(1.4423^n)$
 - Also finds a monopolar partition, if the graph is monopolar
- This talk: a **simpler version** that solves Monopolar Recognition in $\mathcal{O}^*(2^{n/2}) = \mathcal{O}^*(1.4142^n)$ time
- Two FPT algorithms for Monopolar Recognition
 1. $\mathcal{O}^*(3.076^{k_v})$; k_v is the size of a smallest **vertex** modulator to claw-free graphs
 2. $\mathcal{O}^*(2.253^{k_e})$; k_e is the size of a smallest **edge** modulator to claw-free graphs

*Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

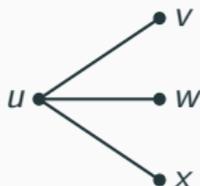
Our Results

- We solve Monopolar Recognition in $\mathcal{O}^*(1.3734^n)$ time
 - Improves on the $\mathcal{O}^*(1.4423^n)$
 - Also finds a monopolar partition, if the graph is monopolar
- This talk: a **simpler version** that solves Monopolar Recognition in $\mathcal{O}^*(2^{n/2}) = \mathcal{O}^*(1.4142^n)$ time
- Two FPT algorithms for Monopolar Recognition
 1. $\mathcal{O}^*(3.076^{k_v})$; k_v is the size of a smallest **vertex** modulator to claw-free graphs
 2. $\mathcal{O}^*(2.253^{k_e})$; k_e is the size of a smallest **edge** modulator to claw-free graphs
- Previous work*: $\mathcal{O}^*(2^{k_c})$ algorithm for Monopolar Recognition
 - k_c is the *number of cliques* on the cluster side
 - Not comparable to either of k_v, k_e

*Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Our Exact Algorithm for Monopolarity: An Overview

- **Known result:** Monopolar Recognition is polynomial-time solvable on *claw-free* graphs[†]
 - Graphs that exclude a **claw** as an *induced* subgraph



[†]Churchley and Huang, *List monopolar partitions of claw-free graphs*, 2012

Our Exact Algorithm for Monopolarity: An Overview

- Monopolar Recognition is easy on claw-free graphs

Our Exact Algorithm for Monopolarity: An Overview

- Monopolar Recognition is easy on claw-free graphs
- Perhaps we can
 1. “Drill down” to a claw-free subgraph H of G ,
 2. Solve Monopolar Recognition on H , and
 3. Lift the solution back to G ?

Our Exact Algorithm for Monopolarity: An Overview

- Monopolar Recognition is easy on claw-free graphs
- Perhaps we can
 1. “Drill down” to a claw-free subgraph H of G ,
 2. Solve Monopolar Recognition on H , and
 3. Lift the solution back to G ?
- (We may need to do this for many such subgraphs $H \dots$)

Our Exact Algorithm for Monopolarity: An Overview

- Monopolar Recognition is easy on claw-free graphs
- Perhaps we can
 1. “Drill down” to a claw-free subgraph H of G ,
 2. Solve Monopolar Recognition on H , and
 3. Lift the solution back to G ?
- (We may need to do this for many such subgraphs $H \dots$)
- This is *roughly* what our algorithm does
 - We stop the drill-down *before* reaching a claw-free subgraph \dots
 - \dots in a certain sense \dots

Our Exact Algorithm for Monopolarity: An Overview

Lemma

Any monopolar graph with monopolar partition $V = C \uplus I$ has a claw-free modulator M such that $M \subseteq C$.

Our Exact Algorithm for Monopolarity: An Overview

Lemma

Any monopolar graph with monopolar partition $V = C \uplus I$ has a **claw-free modulator** M such that $M \subseteq C$.

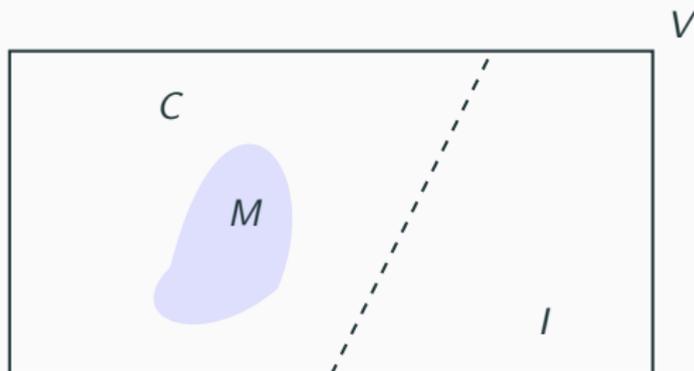
- This is a **vertex** subset whose deletion leaves a claw-free graph

Our Exact Algorithm for Monopolarity: An Overview

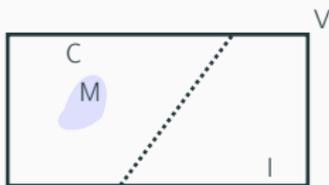
Lemma

Any monopolar graph with monopolar partition $V = C \uplus I$ has a **claw-free modulator** M such that $M \subseteq C$.

- This is a **vertex** subset whose deletion leaves a claw-free graph
- The subgraph $G[M]$ is not necessarily claw-free!

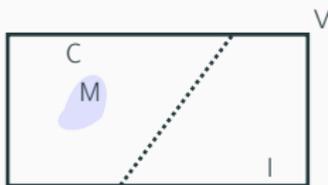


Our Exact Algorithm for Monopolarity: An Overview



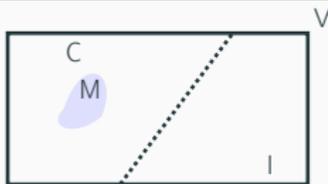
- If G is monopolar, then G has a claw-free modulator M which lives entirely inside the cluster part of *some* monopolar partition of G .
 - We say that such an M is *good*.

Our Exact Algorithm for Monopolarity: An Overview



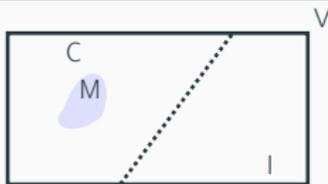
- If G is monopolar, then G has a claw-free modulator M which lives entirely inside the cluster part of *some* monopolar partition of G .
 - We say that such an M is *good*.
- It is **not** true that an *arbitrary* claw-free modulator of G can be made to live inside the cluster part of G .

Our Exact Algorithm for Monopolarity: An Overview



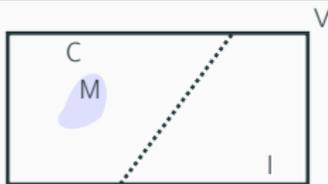
- Every monopolar graph G has a good claw-free modulator M .

Our Exact Algorithm for Monopolarity: An Overview



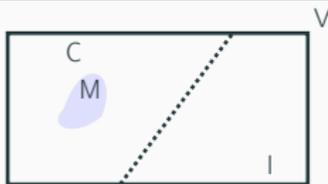
- Every monopolar graph G has a good claw-free modulator M .
- Our algorithm (simplified version):
 1. Branches on induced claws: *guess* a good claw-free modulator M

Our Exact Algorithm for Monopolarity: An Overview



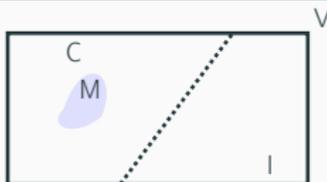
- Every monopolar graph G has a good claw-free modulator M .
- Our algorithm (simplified version):
 1. Branches on induced claws: *guess* a good claw-free modulator M
 2. Checks for a monopolar partition $V = C \uplus I$ with $M \subseteq C$
 - In polynomial time

Our Exact Algorithm for Monopolarity: An Overview



- Every monopolar graph G has a good claw-free modulator M .
- Our algorithm (simplified version):
 1. Branches on induced claws: *guess* a good claw-free modulator M
 2. Checks for a monopolar partition $V = C \uplus I$ with $M \subseteq C$
 - In polynomial time
- The first step needs some care, to make the branching faster

Our Exact Algorithm for Monopolarity: An Overview



- Every monopolar graph G has a good claw-free modulator M .
- Our algorithm (simplified version):
 1. Branches on induced claws: *guess* a good claw-free modulator M
 2. Checks for a monopolar partition $V = C \uplus I$ with $M \subseteq C$
 - In polynomial time
- The first step needs some care, to make the branching faster
- The second step is the non-trivial part

Our Exact Algorithm for Monopolarity: The non-trivial part



- Goal: Check if a claw-free modulator $M \subseteq V$ is good or not
 1. If $G[M]$ is **not** a cluster graph: discard this guess

Our Exact Algorithm for Monopolarity: The non-trivial part



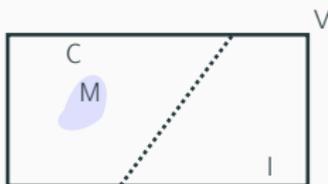
- Goal: Check if a claw-free modulator $M \subseteq V$ is good or not
 1. If $G[M]$ is **not** a cluster graph: discard this guess
 2. If $G - M$ is not monopolar: G is not monopolar either

Our Exact Algorithm for Monopolarity: The non-trivial part



- Goal: Check if a claw-free modulator $M \subseteq V$ is good or not
 1. If $G[M]$ is **not** a cluster graph: discard this guess
 2. If $G - M$ is not monopolar: G is not monopolar either
 3. If $G - M$ **is** monopolar: we are stuck
 - Not clear how to check if M is good
 - $G - M$ can have exponentially-many monopolar partitions
 - (E.g.: if $G - M$ is a matching.)
 - How to “extend” M to the “correct” cluster part of G ?

Our Exact Algorithm for Monopolarity: The non-trivial part



- We show that we can do the non-trivial part in polynomial time

Lemma

Given an arbitrary graph G and a claw-free vertex modulator M of G , we can check if G has a monopolar partition where all of M belongs to the cluster part in polynomial time.

Checking if a given claw-free modulator is good

Our (simpler) algorithm \mathcal{A} solves

- **Input:** Graph $G = (V, E)$, claw-free vertex modulator $M \subseteq V$
 - Where $G[M]$ is a cluster graph
 - **Question:** Is there a monopolar partition $V = C \uplus I$ with $M \subseteq C$?
-

A special case, solved by Le and Nevries[‡]

- **Input:** Claw-free graph $G = (V, E)$, vertex subset $M \subseteq V$
 - Where $G[M]$ is a cluster graph
 - **Question:** Is there a monopolar partition $V = C \uplus I$ with $M \subseteq C$?
-

- We generalize this to *arbitrary* graphs G and their *claw-free* modulators M

[‡]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

Our Algorithms for Monopolarity: High-level overview

- Algorithm \mathcal{A} :
 1. Runs in polynomial time
 2. Checks if a given claw-free modulator M is good

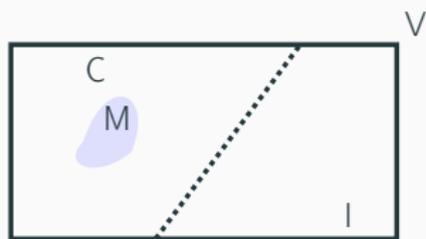
Our Algorithms for Monopolarity: High-level overview

- Algorithm \mathcal{A} :
 1. Runs in polynomial time
 2. Checks if a given claw-free modulator M is good
- The $\mathcal{O}^*(2^{n/2})$ algorithm for Monopolar Recognition:
 1. Branch on induced claws:
 - Go over all potentially good claw-free modulators M
 - In $\mathcal{O}^*(2^{n/2})$ time
 2. Apply algorithm \mathcal{A} on each such M

Our Algorithms for Monopolarity: High-level overview

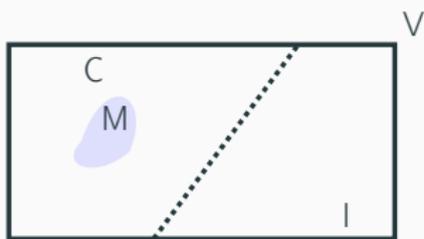
- Algorithm \mathcal{A} :
 1. Runs in polynomial time
 2. Checks if a given claw-free modulator M is good
- The $\mathcal{O}^*(2^{n/2})$ algorithm for Monopolar Recognition:
 1. Branch on induced claws:
 - Go over all potentially good claw-free modulators M
 - In $\mathcal{O}^*(2^{n/2})$ time
 2. Apply algorithm \mathcal{A} on each such M
- The FPT algorithms:
 1. Find *one* claw-free vertex modulator
 - Using standard techniques
 2. Guess the intersection of M with this modulator
 3. Compute the rest of M
 4. Apply algorithm \mathcal{A} on this M

Checking if a claw-free modulator M is good



“Is my M like this?”

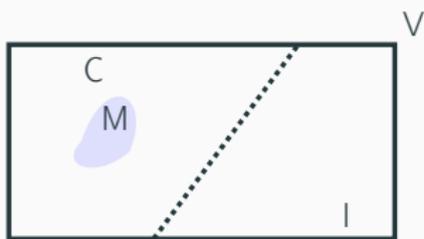
Checking if a claw-free modulator M is good



"Is my M like this?"

- If **no** induced P_3 : trivial

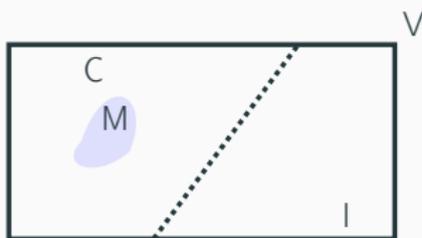
Checking if a claw-free modulator M is good



“Is my M like this?”

- If **no** induced P_3 : trivial
- If G has induced P_3 s: Look at small induced subgraphs that *contain* them
 - How they interact with M
 - Where they could potentially lie in a monopolar partition

Checking if a claw-free modulator M is good



“Is my M like this?”

- If **no** induced P_3 : trivial
- If G has induced P_3 s: Look at small induced subgraphs that *contain* them
 - How they interact with M
 - Where they could potentially lie in a monopolar partition
- Use this to **construct a 2SAT formula** $\phi \equiv M$ is good
 - Building on Le and Nevries' arguments
 - (These worked when the graph G had no claws)

Small induced subgraphs

- The six connected graphs on four vertices:



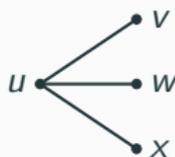
(a) P_4



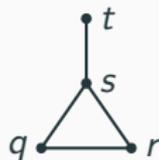
(b) C_4



(c) K_4



(d) Claw



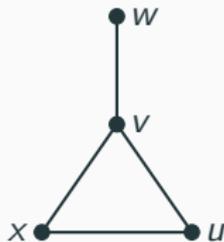
(e) Paw
 $P(s, t)$



(f) Diamond
 $D(s, t)$

- Each induced P_3 is a part of at least one such subgraph.

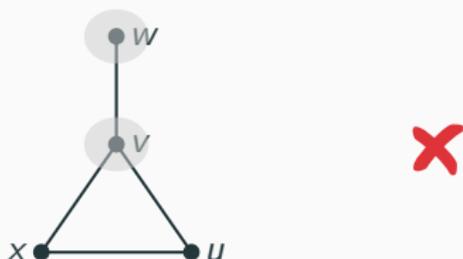
- Example[§]: Induced P_3 is part of a Paw $P(v, w)$.



[§]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

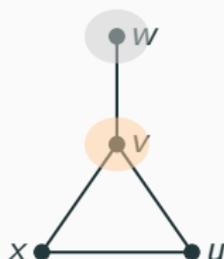
Handling the P_3 s

- Example[§]: Induced P_3 is part of a Paw $P(v, w)$.



[§]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

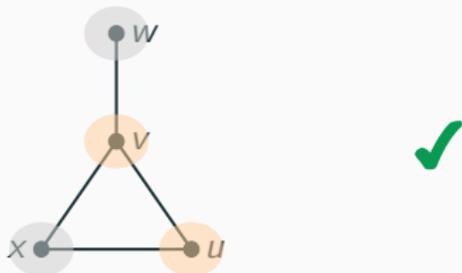
- Example[§]: Induced P_3 is part of a Paw $P(v, w)$.



[§]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

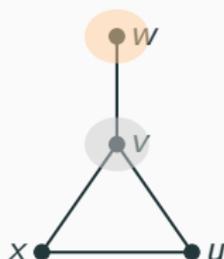
Handling the P_3 s

- Example[§]: Induced P_3 is part of a Paw $P(v, w)$.



[§]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

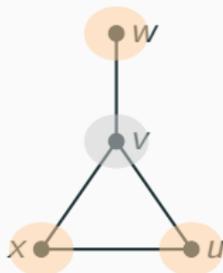
- Example[§]: Induced P_3 is part of a Paw $P(v, w)$.



[§]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

Handling the P_3 s

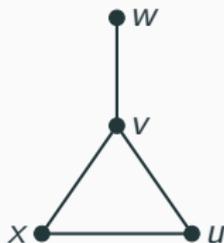
- Example[§]: Induced P_3 is part of a Paw $P(v, w)$.



[§]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

Handling the P_3 s

- Example[§]: Induced P_3 is part of a Paw $P(v, w)$.



- So, in any monopolar partition, either v or w is in the cluster part.
- Likewise, we decide constraints for other small graphs.
- Along with the main constraint of all vertices in M should be assigned to cluster part, we get a 2SAT instance.

[§]Le and Nevries, *Complexity and algorithms for recognizing polar and monopolar graphs*, 2014

Handling the remaining P_3 s

- But, our graph may have induced P_3 s far away from set M - no neighbours in M , not part of any small subgraphs.

Handling the remaining P_3 s

- But, our graph may have induced P_3 s far away from set M - no neighbours in M , not part of any small subgraphs.
- We show that we can get rid of such P_3 s and then apply Le and Nevries's 2SAT lemma
 - This is our main technical insight

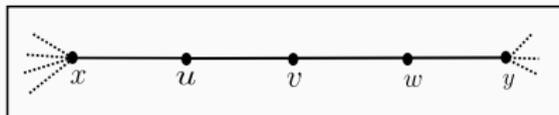
¹Plus some more conditions

Handling the remaining P_3 s

- But, our graph may have induced P_3 s far away from set M - no neighbours in M , not part of any small subgraphs.
- We show that we can get rid of such P_3 s and then apply Le and Nevries's 2SAT lemma
 - This is our main technical insight

Lemma

Let M be a claw-free vertex modulator of graph G . If uvw is an induced P_3 in G which does not have a neighbour[¶] in M , then *all* the vertices u, v, w are of degree **exactly** 2 in G .



[¶]Plus some more conditions

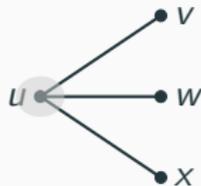
Branching on an induced claw

How to branch to a claw-free modulator M ?



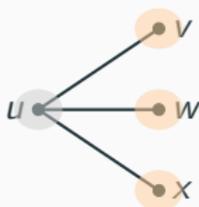
Branching on an induced claw

How to branch to a claw-free modulator M ?



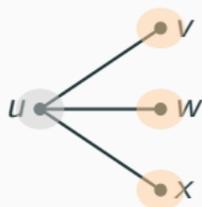
Branching on an induced claw

How to branch to a claw-free modulator M ?



Branching on an induced claw

How to branch to a claw-free modulator M ?

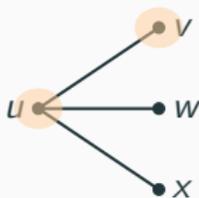


Put v, w, x to M

Measure drops by 4

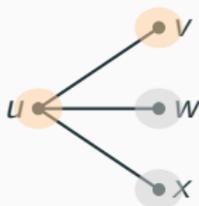
Branching on an induced claw

How to branch to a claw-free modulator M ?



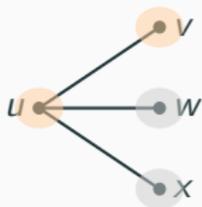
Branching on an induced claw

How to branch to a claw-free modulator M ?



Branching on an induced claw

How to branch to a claw-free modulator M ?

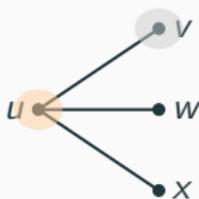


Put u, v to M

Measure drops by 4

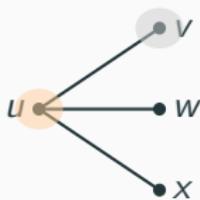
Branching on an induced claw

How to branch to a claw-free modulator M ?



Branching on an induced claw

How to branch to a claw-free modulator M ?

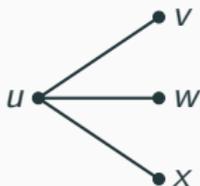


Put u to M , no other implication

Measure drops by just 2

Branching on an induced claw

How to branch to a claw-free modulator M ?



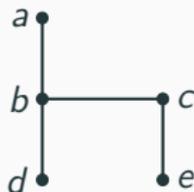
- Three-way branching
- The number of undecided vertices drops by $(4, 4, 2)$
- Branching tree with $O(2^{n/2})$ nodes

The faster $\mathcal{O}^*(1.3734^n)$ algorithm

- Main insights of the faster algorithm are:

The faster $\mathcal{O}^*(1.3734^n)$ algorithm

- Main insights of the faster algorithm are:
 - The non-trivial part of deciding if a **chair-free** vertex modulator is good can still be solved in *polynomial* time.
 - There exists a strategy to branch *faster* towards these modulators.



Our algorithm \mathcal{A} solves

- **Input:** Graph $G = (V, E)$, **chair-free** vertex modulator $M \subseteq V$
 - Where $G[M]$ is a cluster graph
 - **Question:** Is there a monopolar partition $V = C \uplus I$ with $M \subseteq C$?
-

Some open problems

1. Can we improve on the exact exponential running time?

|| Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Some open problems

1. Can we improve on the exact exponential running time?
 - ETH lower bound^{||}: $\mathcal{O}^*(2^{\Omega(m+n)}) = \mathcal{O}^*(2^{\Omega(n)})$

^{||} Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Some open problems

1. Can we improve on the exact exponential running time?
 - ETH lower bound^{||}: $\mathcal{O}^*(2^{\Omega(m+n)}) = \mathcal{O}^*(2^{\Omega(n)})$
2. Can we solve *polar* recognition faster than $\mathcal{O}^*(2^n)$?

^{||} Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Some open problems

1. Can we improve on the exact exponential running time?
 - ETH lower bound^{||}: $\mathcal{O}^*(2^{\Omega(m+n)}) = \mathcal{O}^*(2^{\Omega(n)})$
2. Can we solve *polar* recognition faster than $\mathcal{O}^*(2^n)$?
 - Perhaps using our algorithm for monopolarity as a starting point?

^{||} Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Some open problems

1. Can we improve on the exact exponential running time?
 - ETH lower bound^{||}: $\mathcal{O}^*(2^{\Omega(m+n)}) = \mathcal{O}^*(2^{\Omega(n)})$
2. Can we solve *polar* recognition faster than $\mathcal{O}^*(2^n)$?
 - Perhaps using our algorithm for monopolarity as a starting point?
3. FPT algorithms for Monopolar Recognition *without* finding a small modulator to claw-free graphs?

^{||} Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Some open problems

1. Can we improve on the exact exponential running time?
 - ETH lower bound^{||}: $\mathcal{O}^*(2^{\Omega(m+n)}) = \mathcal{O}^*(2^{\Omega(n)})$
2. Can we solve *polar* recognition faster than $\mathcal{O}^*(2^n)$?
 - Perhaps using our algorithm for monopolarity as a starting point?
3. FPT algorithms for Monopolar Recognition *without* finding a small modulator to claw-free graphs?
 - The bottleneck in our algorithms is finding these modulators.

^{||} Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Some open problems

1. Can we improve on the exact exponential running time?
 - ETH lower bound^{||}: $\mathcal{O}^*(2^{\Omega(m+n)}) = \mathcal{O}^*(2^{\Omega(n)})$
2. Can we solve *polar* recognition faster than $\mathcal{O}^*(2^n)$?
 - Perhaps using our algorithm for monopolarity as a starting point?
3. FPT algorithms for Monopolar Recognition *without* finding a small modulator to claw-free graphs?
 - The bottleneck in our algorithms is finding these modulators.
4. Find a (vertex, or edge) modulator to claw-free graphs in faster FPT time?

^{||} Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Some open problems

1. Can we improve on the exact exponential running time?
 - ETH lower bound^{||}: $\mathcal{O}^*(2^{\Omega(m+n)}) = \mathcal{O}^*(2^{\Omega(n)})$
2. Can we solve *polar* recognition faster than $\mathcal{O}^*(2^n)$?
 - Perhaps using our algorithm for monopolarity as a starting point?
3. FPT algorithms for Monopolar Recognition *without* finding a small modulator to claw-free graphs?
 - The bottleneck in our algorithms is finding these modulators.
4. Find a (vertex, or edge) modulator to claw-free graphs in faster FPT time?
 - We used the d-Hitting Set algorithm as a black box

^{||} Kanj et al., *Parameterized algorithms for recognizing monopolar and 2-subcolorable graphs*, 2018

Thank you!