

# Dequantization Barriers for Guided Stochastic Hamiltonians

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Based on joint work with *Yassine Hamoudi* and *Yvan Le Borgne*

<https://arxiv.org/abs/2602.23183>

**LaBRI**

# Ground state information of a many-body system

$m$ -qubit Hamiltonian

$$H \in \mathbb{C}^{2^m \times 2^m}$$



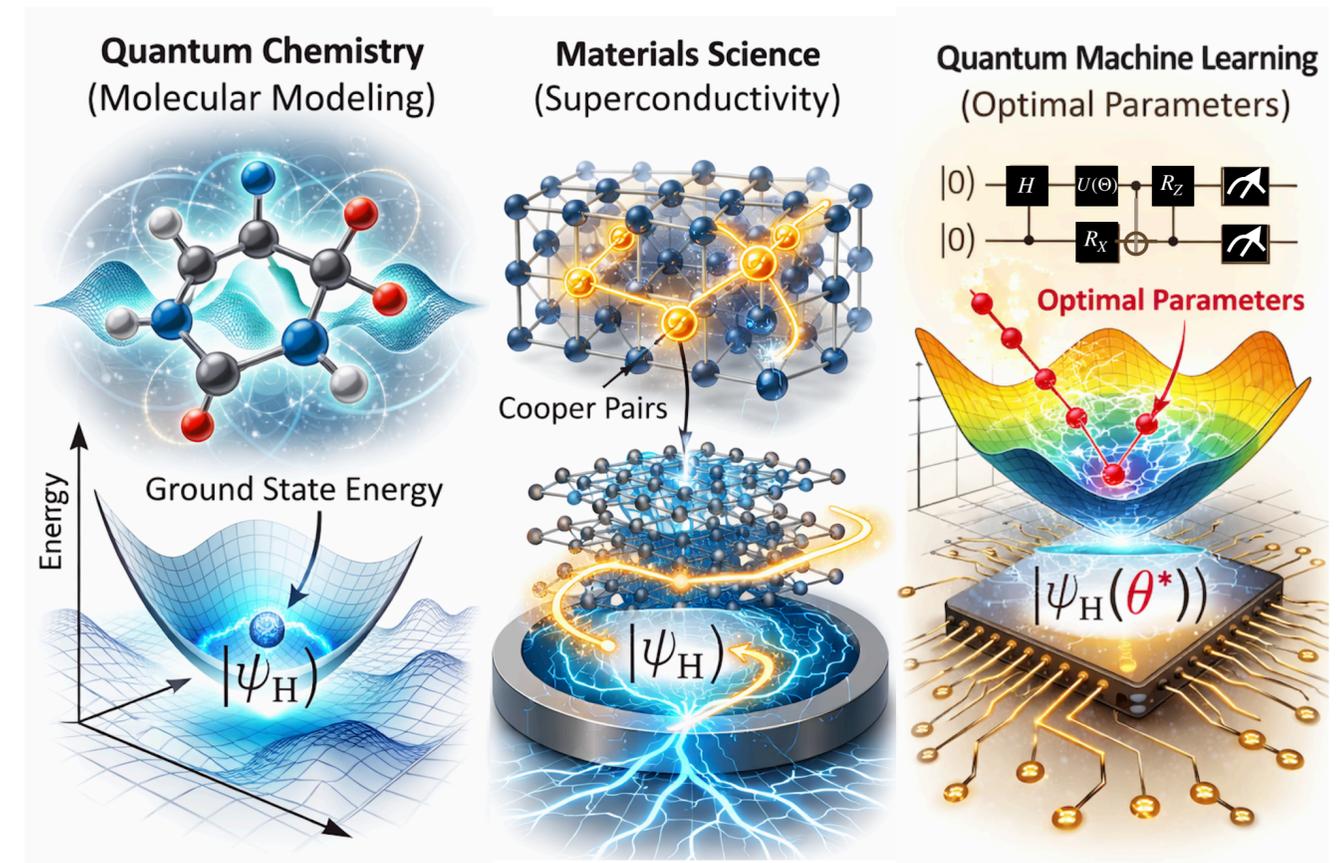
Ground state  $|\psi_H\rangle$ ,  
Ground energy  $\lambda_H$ , etc.,.

Generally **hard** without **extra** information  
even for quantum computers

Ex: Computing  $\lambda_H \pm \delta$  is **QMA-Hard** for *local*  $H$

Hardness quantified by:

Number of gates, number of qubits, queries etc.,.



# Preparing the ground state $|\psi_H\rangle$

Given access to  $H$ , prepare the ground state  $|\psi_H\rangle$

**More general than** estimating  $\lambda_H \implies$  believed to be **hard** even for quantum

But, significantly **easier** when given the following **extra** information

**Guiding state**  $|\psi_{\text{in}}\rangle$ :  $\langle \psi_{\text{in}} | \psi_H \rangle = \text{large}$

*Ansatz* - QAOA, Variational Quantum Algorithms

Notion similar to

*Warm starts* - Markov chain Monte Carlo

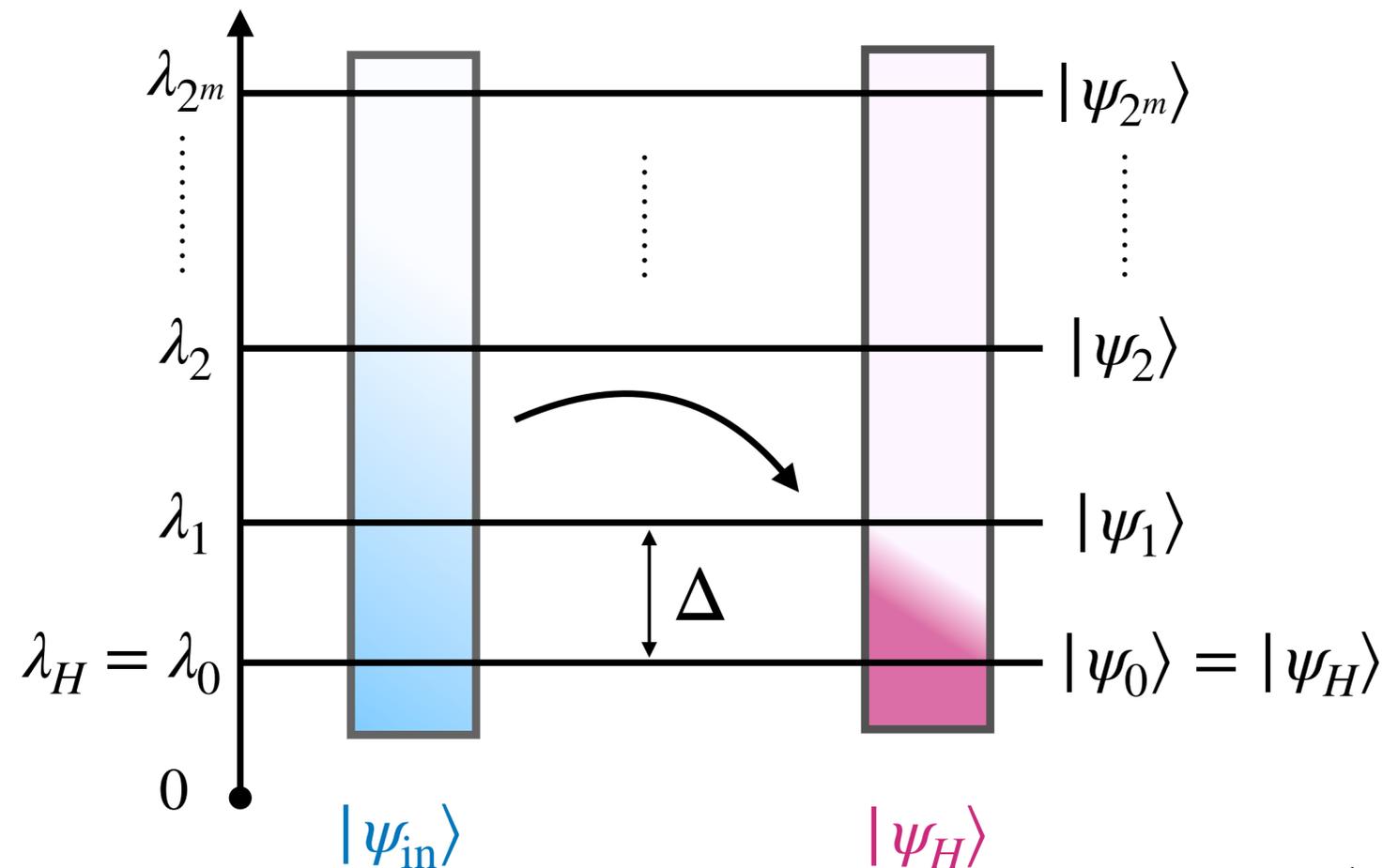
*Intermediate states* - Adiabatic Quantum Computation

# Complexity of guided ground state preparation

## Guided Ground State Preparation (GGSP)

Given access to  $H$  and a *guiding* state  $|\psi_{\text{in}}\rangle$ , prepare the ground state  $|\psi_H\rangle$

GGSP is quantumly *efficient* for **sufficiently large** overlap



Filter out  $|\psi_H\rangle^\perp$  from  $|\psi_{\text{in}}\rangle$  using QPE

Quantum Algorithm using  $|\psi_{\text{in}}\rangle$ ,  
prepares  $|\psi_H\rangle$  in  
 $\text{poly}\left(m, \frac{1}{\Delta}, \frac{1}{\langle\psi_{\text{in}}|\psi_H\rangle}\right)$  time\*

\*Under some reasonable assumptions

# Complexity of Guided Ground State Preparation

Given access to  $H$  and a *guiding* state  $|\psi_{\text{in}}\rangle$ , prepare the ground state  $|\psi_H\rangle$

GGSP is efficiently solvable on *quantum computer* for *sufficiently large* overlap

Is there an *efficient* classical algorithm for GGSP?

François Le Gall, 2025

Computing  $\lambda_H \pm \delta$  for *guided local*  $H$  classically takes poly  $\left( \frac{1}{\langle \psi_{\text{in}} | \psi_H \rangle^{1/\delta}}, m \right)$  time

Can GGSP be *dequantized* as well?

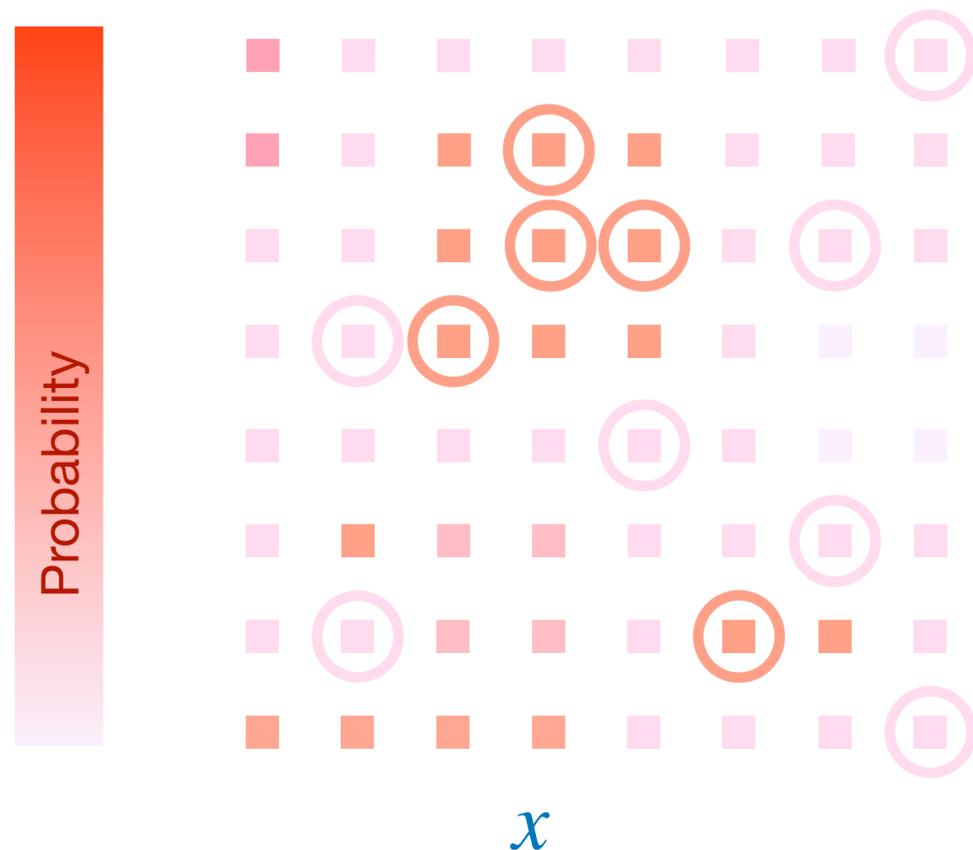
# Classical Complexity of GGSP

Can GGSP be **dequantized** as well?

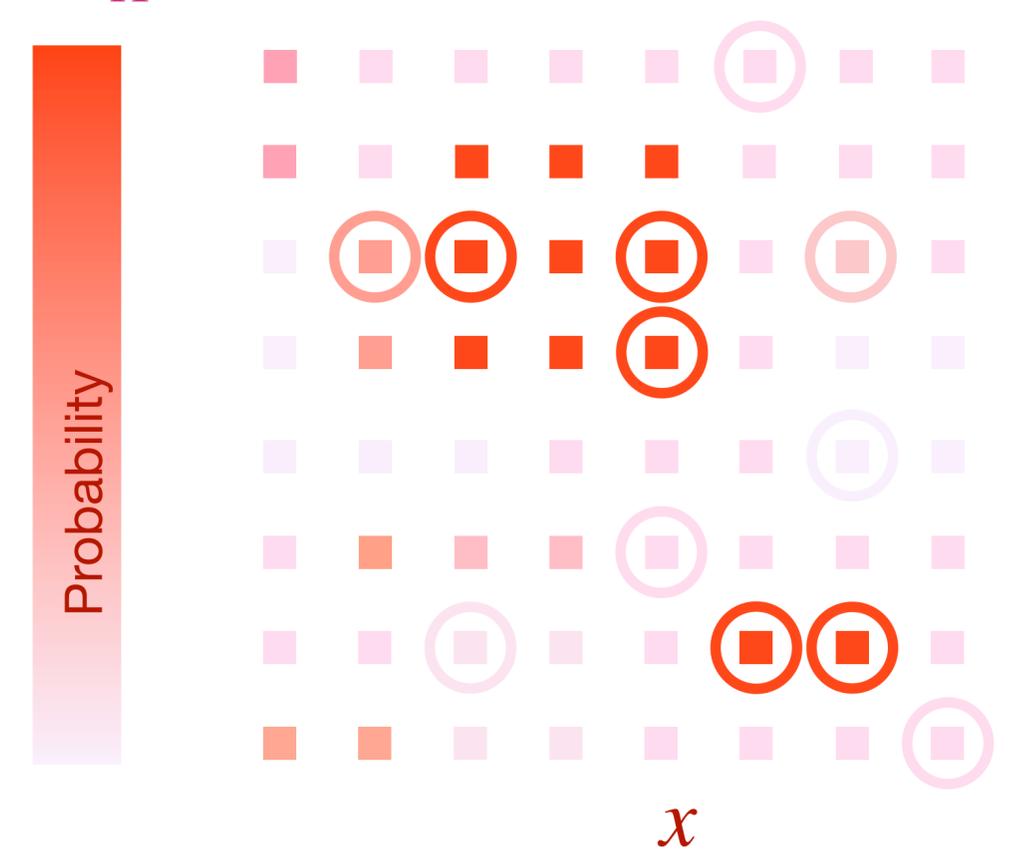
What does  $|\psi_{\text{in}}\rangle$  mean *classically*?

What does *preparing*  $|\psi_H\rangle$  mean *classically*?

$$|\langle x | \psi_{\text{in}} \rangle|^2$$



$$|\langle x | \psi_H \rangle|^2$$



# Classical Complexity of Stoquastic GGSP

First step: Is GGSP *classically* easy when  $H$  is *stoquastic*?

Stoquastic Hamiltonian

$$H = \begin{pmatrix} h_{11} & \leq 0 & \dots & \leq 0 \\ \leq 0 & h_{22} & \ddots & \vdots \\ \vdots & \ddots & \ddots & \leq 0 \\ \leq 0 & \dots & \leq 0 & h_{2^m 2^m} \end{pmatrix}$$

*In some basis*



Perron-Frobenius theorem

$$\langle x | \psi_H \rangle \geq 0 \text{ for all } x$$

Hamiltonians without sign problem

Classical optimisation functions - diagonal,

Transverse Field Ising Model,

Quantum architectures: D-Wave, etc.,.

GGSP is *classically easy* for *stoquastic + frustration free*

[Bravyi and Terhal'10]

# Classical Complexity of Stoquastic GGSP

Is GGSP *classically* easy when  $H$  is *stoquastic*?

Gilyén, Hastings and Vazirani; 2021

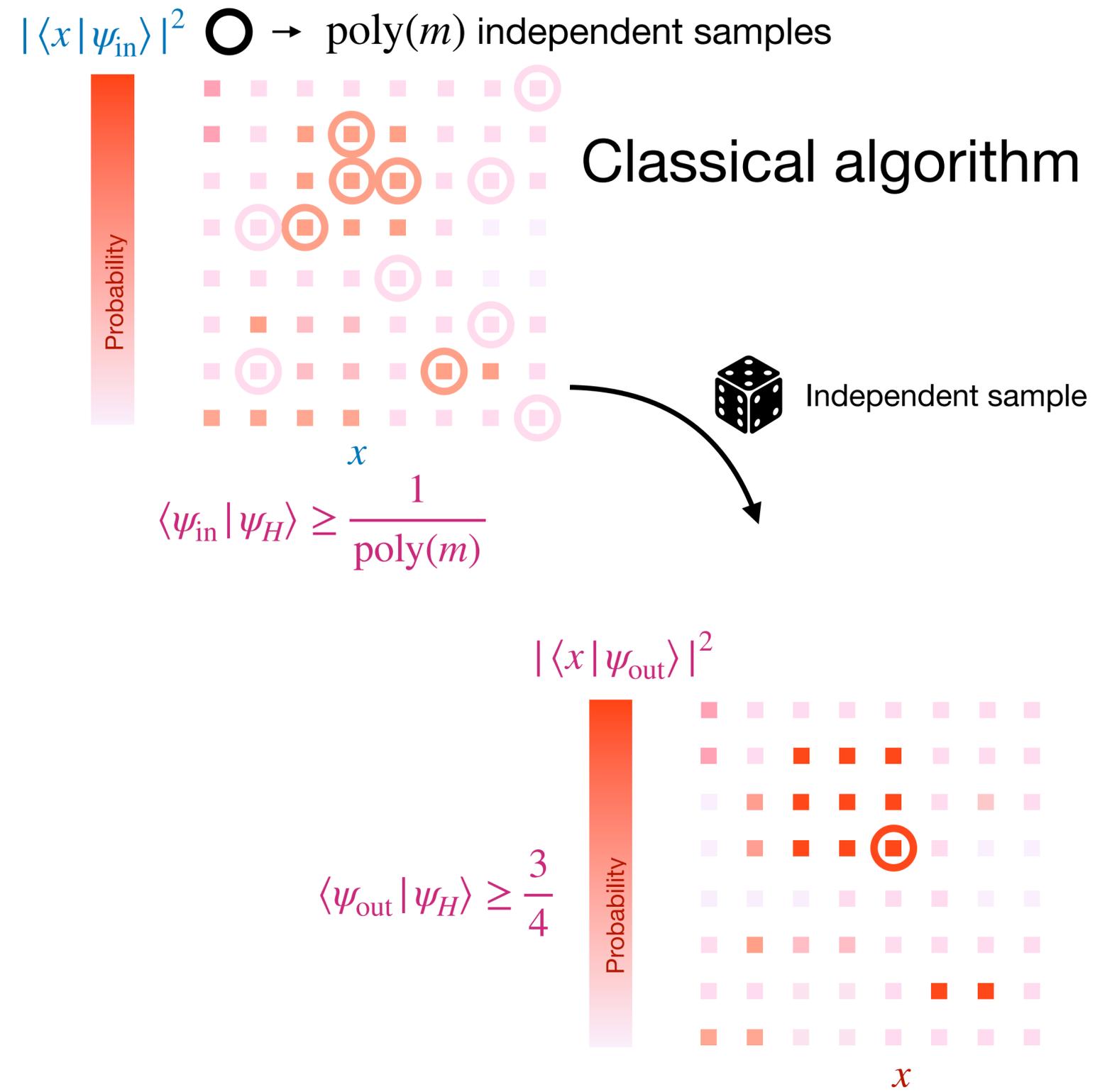
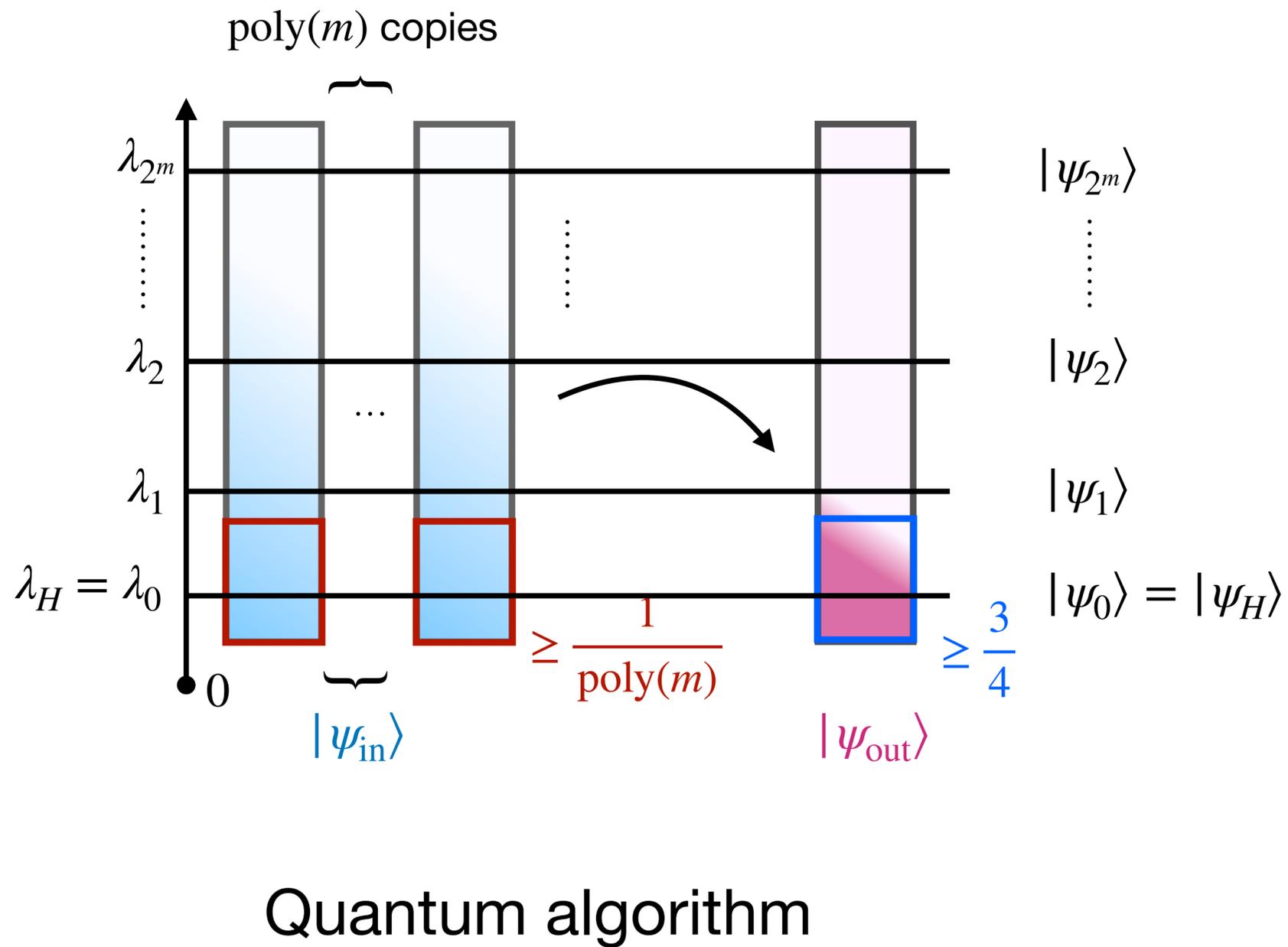
$\exists$  a stoquastic  $H$ : *classically* **hard** to prepare  $|\psi_H\rangle$  given a **particular**  $|\psi_{\text{in}}\rangle$   
whereas it is *quantumly* easy to prepare  $|\psi_H\rangle$

**Our result**

$\exists$  a stoquastic  $H$ : *classically* **hard** to prepare  $|\psi_H\rangle$  given an **arbitrary**  $|\psi_{\text{in}}\rangle$   
whereas it is *quantumly* easy to prepare  $|\psi_H\rangle$

\*Both hardness results are in terms of number of queries to a resource

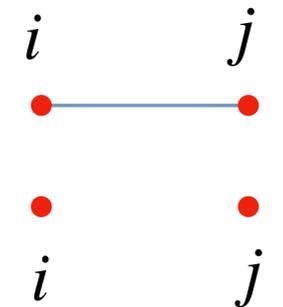
# Formal problem statement



# Proof sketch: Construction of $H$

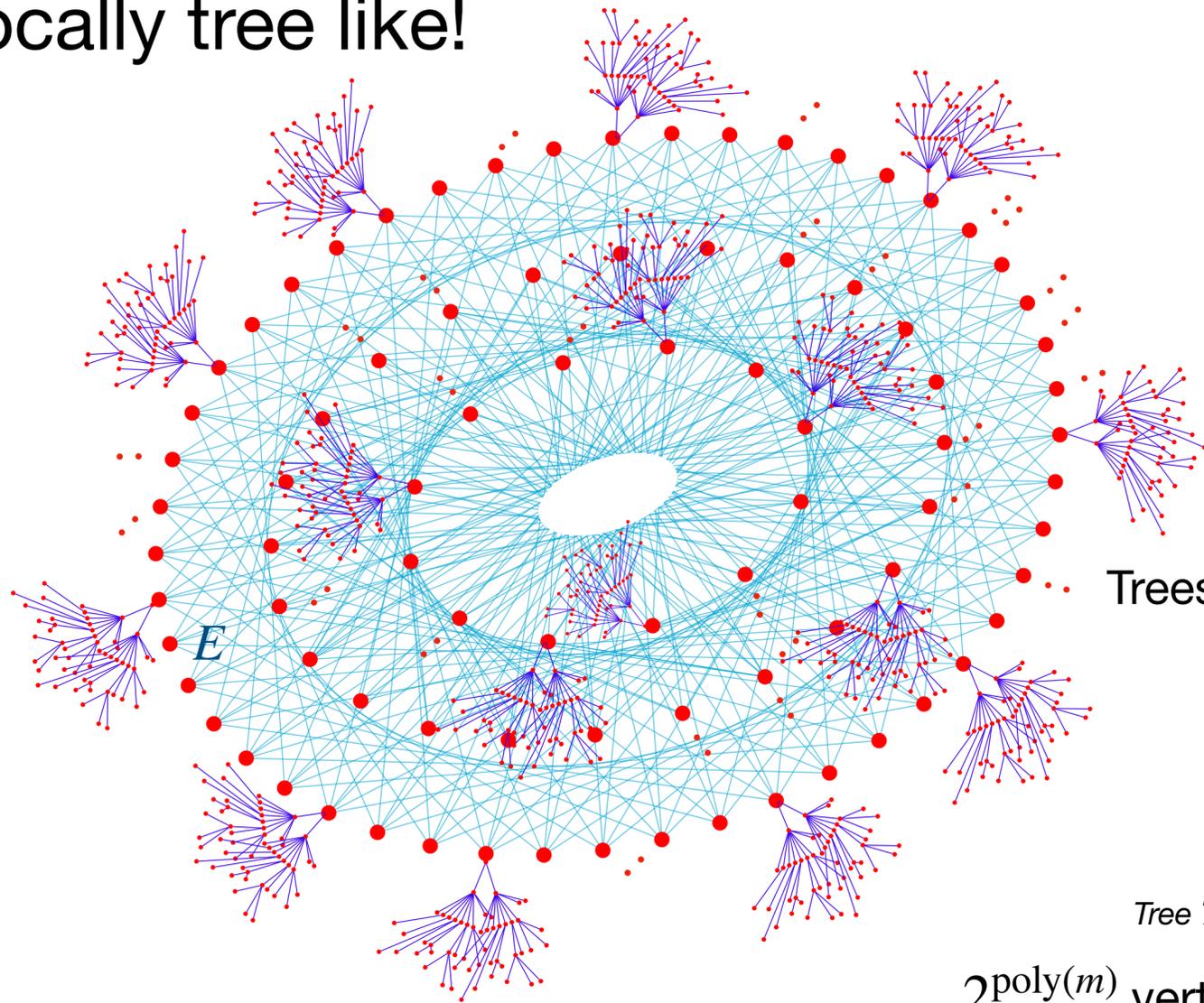
Expander  $E$  - large *girth* and large *gap*  
 Locally tree like!

$$H = -A_G$$

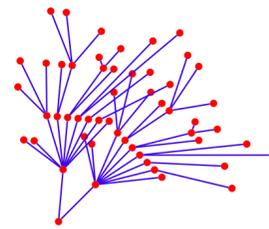
$$\langle i | H | j \rangle = \begin{cases} -1 & \text{if } i \text{ --- } j \\ 0 & \text{if } i \text{ and } j \text{ are not adjacent} \end{cases}$$


**Stoquastic!**

$|\psi_H\rangle =$  top eigenvector of  $A_G$

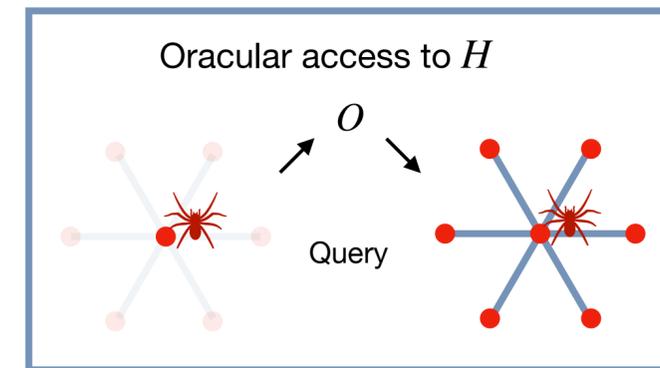


Trees match local picture of  $E$



Tree  $T$  - On all vertices

$2^{\text{poly}(m)}$  vertices in  $T$  as well



**Hard/Easy** - More/Less queries to  $O$

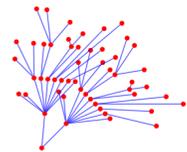
$2^{\text{poly}(m)}$  vertices

$G$



$\exists$  a quantum algorithm for GGSP performing  $\text{poly}(m)$  queries

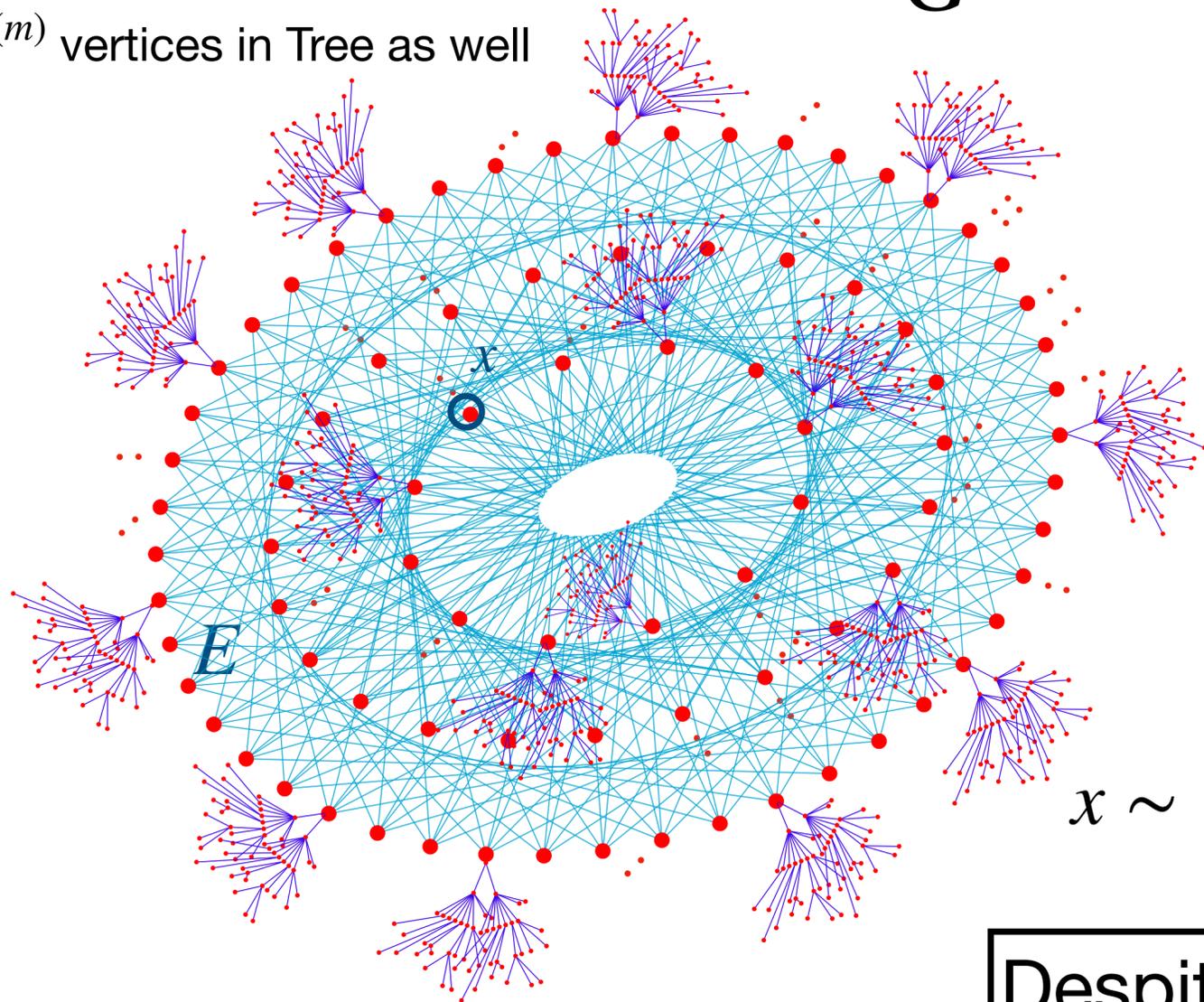
# Concentration property of $|\psi_H\rangle$



Tree on all vertices

$$H = -A_G$$

$2^{\text{poly}(m)}$  vertices in Tree as well



$E$

$2^{\text{poly}(m)}$  vertices  $G$

Concentration Property of  $|\psi_H\rangle$

$$|\langle \text{Trees} | \psi_H \rangle|^2 = o(1) \quad \text{Very tiny}$$

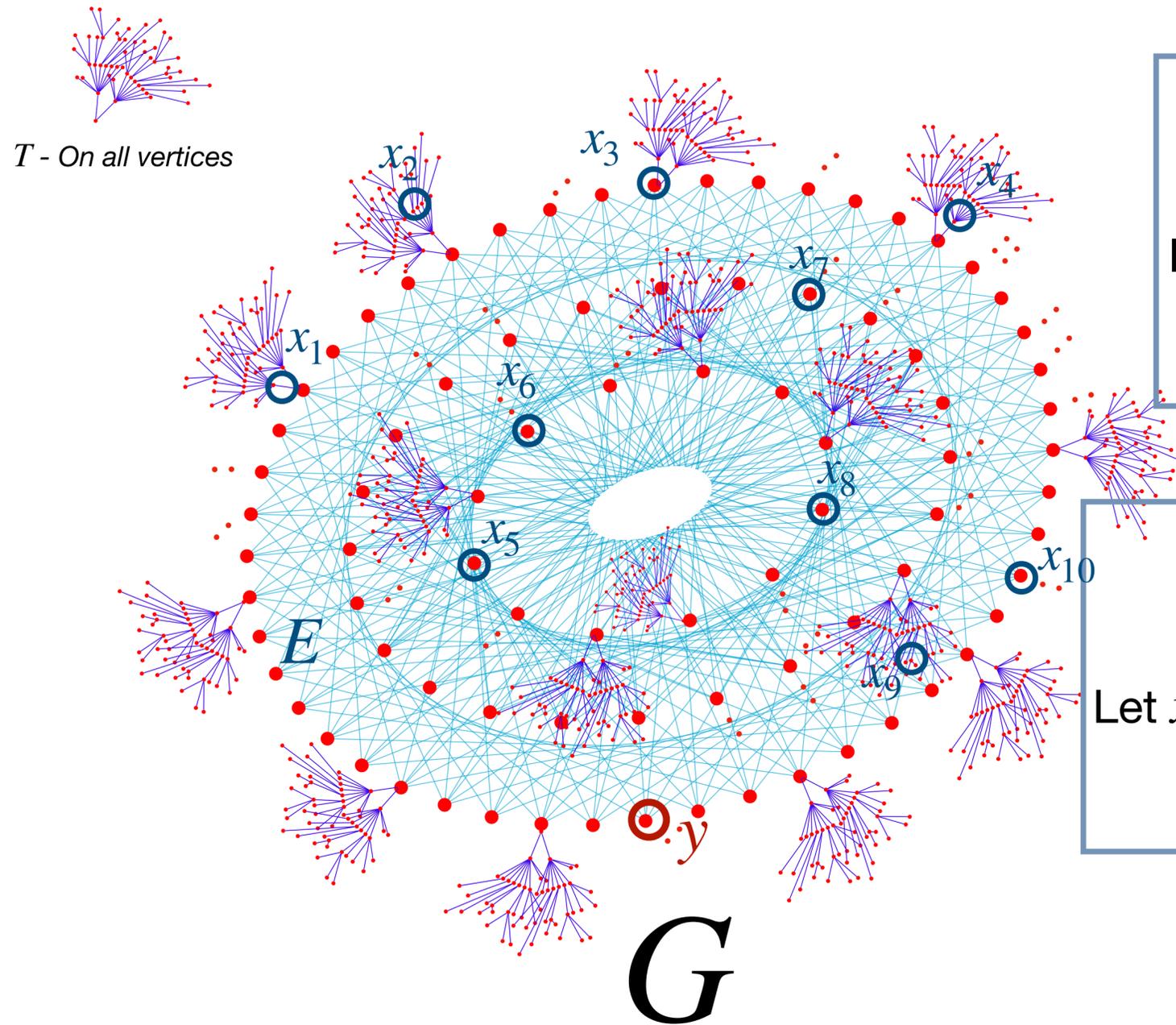
$$|\langle \text{Expander} | \psi_H \rangle|^2 = 1 - o(1) \quad \text{Very large}$$



$$x \sim |\langle x | \psi_H \rangle|^2 \implies x \in \text{Expander, with high probability}$$

Despite each **tree** having **huge** number of vertices!

# Proof sketch: Localization

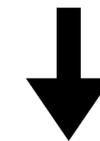


## Localization Property of $|\psi_H\rangle$

If  $x_1, x_2, \dots, x_t \sim \left( |\langle x_i | \psi_H \rangle|^2 \right)^{\otimes t}$ , then they are **far** from each other with high probability

## Localization Property for **all** $|\psi_{in}\rangle, |\psi_{out}\rangle$

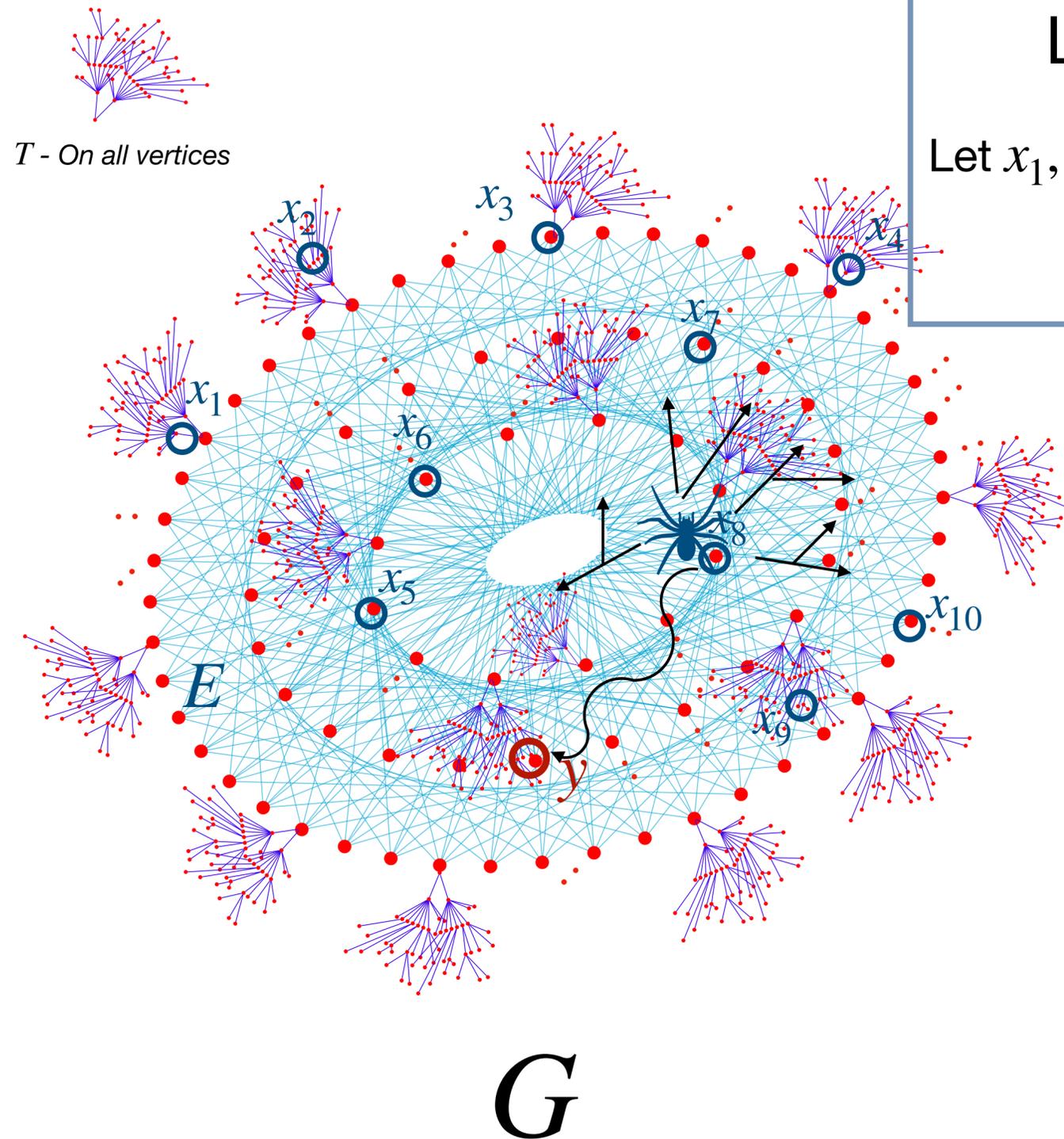
Let  $x_1, x_2, \dots, x_t \sim \left( |\langle x_i | \psi_{in} \rangle|^2 \right)^{\otimes t}$ . If  $y \sim |\psi_{out}\rangle$ , then  $y$  is **far** from all  $x_i$ s with high probability



**Any** classical algorithm solving GGSP must **output** a  $y$  **far** from all  $x_i$ s

Note that this is for all guiding states!

# Proof sketch: Localization



Localization Property for **any**  $|\psi_{\text{in}}\rangle, |\psi_{\text{out}}\rangle$

Let  $x_1, x_2, \dots, x_t \sim \left( |\langle x_i | \psi_{\text{in}} \rangle|^2 \right)^{\otimes t}$ . If  $y \sim |\psi_{\text{out}}\rangle$ , then  $y$  is **far** from all  $x_i$ s  
with high probability

But, only oracle access to  $H$

Classical algorithms can perform only  
**local exploration of  $G$**  from  $x_i$ s



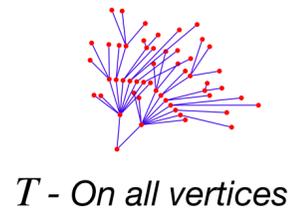
**Any** classical algorithm solving GGSP  
must **explore** a  $y$  **far** from all  $x_i$ s

with high probability

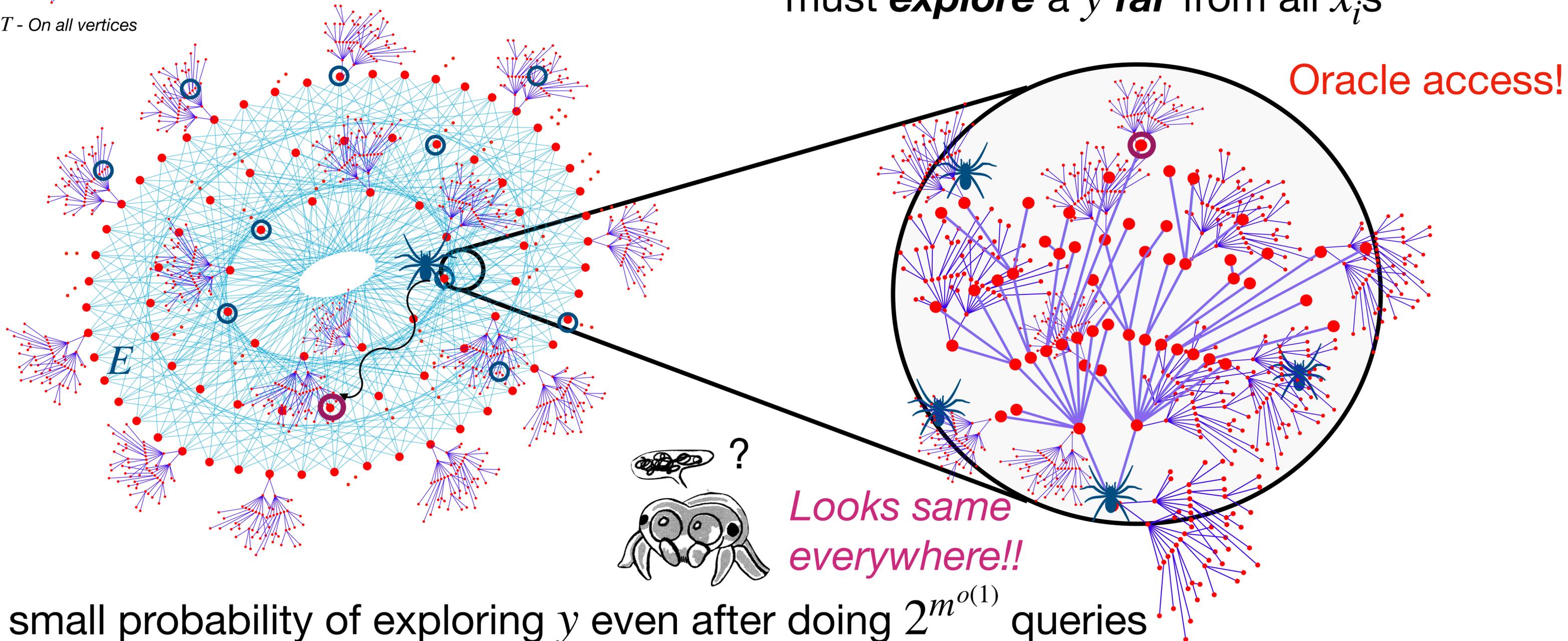
# Proof sketch: How difficult is it to find a far $y$ ?

This is very difficult! **X**

**Any** classical algorithm solving GGSP must **explore** a **far**  $y$  from all  $x_i$ s



$G$



Very small probability of exploring  $y$  even after doing  $2^{m^{o(1)}}$  queries

# Conclusion

## Our result

$\exists$  a **stoquastic**  $H$ : classically **hard**  $\left(2^{m^{o(1)}}\right)$  to prepare  $|\psi_H\rangle$  given an **arbitrary**  $|\psi_{\text{in}}\rangle$  whereas it is quantumly **easy**  $\left(\text{poly}(m)\right)$  to prepare  $|\psi_H\rangle$

Rules out *dequantized* algorithms for GGSP given **arbitrary**  $|\psi_{\text{in}}\rangle$

Rules out *dequantization of adiabatic paths* that go through our  $H$

Open question 1

Is there a stoquastic  $H$ : classically hard  $\left(2^{O(m)}\right)$  to prepare  $|\psi_H\rangle$  but easy  $\left(\text{poly}(m)\right)$  to prepare  $|\psi_H\rangle$  quantumly ?

Open question 2

What is the classical complexity of GGSP for local  $H$ ?